

Objective Assessment of the Effects of Tumor Motion in Radiation Therapy

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Abstract

Purpose: Internal organ motion reduces the accuracy and efficacy of radiation therapy. However, there is a lack of tools to objectively (based on a medical or scientific task) assess the dosimetric consequences of motion, especially on an individual basis. We propose to use therapy operating characteristic (TOC) analysis to quantify the effects of motion on treatment efficacy for individual patients. We demonstrate the application of this tool with pancreatic stereotactic body radiation therapy (SBRT) clinical data and explore the origin of motion sensitivity.

Methods: The technique is described as follows. (1) Use tumor-motion data measured from patients to calculate the motion-convolved dose of the gross tumor volume (GTV) and the organs at risk (OARs). (2) Calculate tumor control probability (TCP) and normal tissue complication probability (NTCP) from the motion-convolved dose volume histograms. (3) Construct TOC curves from TCP and NTCP models. (4) Calculate the area under the TOC curve (AUTO) and use it as a figure of merit for treatment efficacy. We used tumor motion data measured from patients to calculate the relation between AUTO and motion magnitude for 25 pancreatic SBRT treatment plans. Furthermore, to explore the driving factor of motion sensitivity of a given plan, we compared the dose distribution of motion-sensitive plans and motion-robust plans and studied the dependence of motion sensitivity to motion directions.

Results: Our technique is able to recognize treatment plans that are sensitive to motion. Under the presence of motion, the treatment efficacy of some plans changes from providing high tumor control and low risks of complications to providing no tumor control and high risks of side effects. Several treatment plans experience falloffs in AUTO at a smaller magnitude of motion than other plans. In our dataset, a potential indicator of a motion-sensitive treatment plan is that the duodenum is in close proximity to the tumor in the SI direction.

Conclusions: The TOC framework can serve as a tool to quantify the effects of internal organ motion in radiation therapy. With pancreatic SBRT clinical data, we applied this tool to study the change in treatment efficacy induced by motion for individual treatment plans. This framework could potentially be used clinically to understand the effects of motion in an individual patient and to design a patient-specific motion management plan. This framework could also be used in

research to evaluate different components of the treatment process, such as motion-management techniques, treatment-planning algorithms, treatment margins, etc.

Keywords: tumor motion, treatment efficacy, TCP, NTCP, TOC

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1 I. INTRODUCTION

2 In radiation therapy, internal organ motion is a major concern for all tumor sites in the
3 thorax and abdomen, because it decreases the accuracy of radiation delivery [1–5]. Many
4 studies have assessed the effects of tumor motion in terms of dose distribution metrics, such
5 as: mean dose [6], dose-population histograms [7], coverage probability [8] and individual
6 dose-volume histograms [3]. However, none of these studies relate tumor motion to clinical-
7 based endpoints of radiation therapy.

8 To study the effects of motion on treatment efficacy, we borrowed a generally-accepted
9 concept, 'objective assessment', from the Medical Imaging community. 'Objective' means
10 based on the performance of medically or scientifically relevant tasks [9]. The task in diag-
11 nostic imaging is often to detect an abnormality. Many evaluation methods of the perfor-
12 mance of this task relate to receiver operating characteristic (ROC) analysis, which depicts
13 the trade-off between the probability of detection (true-positive rate) and the false-alarm
14 fraction (false-positive rate) as the decision threshold is varied. ROC analysis and the area
15 under the ROC curve (AUROC) have been used to assess image quality, compare imaging
16 systems and evaluate reconstruction algorithms [10, 11].

17 In cancer radiation therapy, the task is to cure or control tumors while reducing the
18 risk of harming normal tissues. The achievement of this task can be measured through two
19 clinically-based endpoints: the tumor control probability (TCP) [12, 13] and the normal
20 tissue complication probability (NTCP) [14, 15], which correspond to the probability of
21 benefits and the risk of side effects, respectively. TCP and NTCP are models relating
22 clinical outcomes to dose received by tumors and organs at risk (OARs). A variety of
23 mathematical models have been presented to describe the dose-response curves obtained
24 from experiments and clinical trials [16], and standardized modules for the calculation of
25 some models are freely available [17–19]. Furthermore, there are major ongoing efforts to
26 incorporate emerging clinical data into TCP and NTCP modeling [20–22].

27 TCP and NTCP are two inseparable aspects of treatment efficacy, because there are
28 potential trade-offs between the two outcomes. For example, when the treatment dose is
29 increased, TCP increases at the sacrifice of increased NTCP. One way to consider TCP and
30 NTCP simultaneously is to use a therapy operating characteristic (TOC) curve, analogous
31 to an ROC curve. The TOC curve plots TCP vs. NTCP as the treatment dose is varied.

32 TOC curves reflect the therapeutic ratio between TCP and NTCP.

33 TOC was first introduced to the radiotherapy community by Mendelsohn and Moore
34 [23, 24] in 1972 for comparison of treatment protocols. Since then, TOC has been applied
35 to optimize the radiation dose in several disease sites [25–28]. More recently, the area under
36 the TOC curve (AUTOC) [29, 30] has been employed as a figure of merit to evaluate seg-
37 mentation algorithms [31], to assess image quality in radiation therapy [30, 32], to prescribe
38 radiation dose on a per-patient basis [33] and to study treatment efficacy in the field of
39 precision chemotherapy [34]. More specifically, the theory of applying TOC to the study of
40 tumor motion was laid out by Barrett et. al. [30].

41 Tumor motion blurs the planned dose distribution and leads to a deviation between the
42 intended and delivered dose distributions. When motion causes the OARs to move into
43 the high-dose regions of a treatment plan, NTCP increases. Additionally, when motion
44 causes tumors to move out of the treatment volume, TCP decreases. In this way, motion
45 can decrease TCP and increase NTCP, and hence drag the TOC curve from the upper left
46 corner towards the lower right corner. As a result, AUTOC decreases with tumor motion.
47 Therefore, AUTOC can serve as a figure of merit to study the effect of tumor motion on the
48 efficacy of radiation treatment [30].

49 To demonstrate the utility of TOC/AUTOC in studying the clinical effects of motion
50 in radiotherapy, we applied the TOC framework in pancreatic Stereotactic Body Radiation
51 Therapy (SBRT). In recent years, multiple clinical trials have shown encouraging clinical
52 outcomes of pancreatic cancer patients after SBRT [35–38]. However, the safe delivery of
53 pancreatic SBRT is hindered by tumor motion. First, since the motion of the pancreas is
54 often highly irregular, it is hard to account for by the four-dimensional computed tomography
55 (4DCT) images acquired at the time of simulation [39–41]. Secondly, the pancreas is located
56 in close proximity to the duodenum, which is highly sensitive to radiation and hence limits
57 dose escalation in pancreatic SBRT [42].

58 The purpose of our paper is twofold: first, to develop TOC as a tool and AUTOC
59 as a figure of merit for objective (task-based) assessment of the effects of tumor motion
60 on treatment efficacy, and second, to demonstrate the utility of this approach using real-
61 world examples with clinical data. We accomplished this purpose in three steps. First, we
62 developed a TOC framework for quantifying the effect of motion on clinical endpoints. Next,
63 we utilized daily motion data measured from patients in conjunction with clinical treatment

64 plans for pancreatic cancer. With these data, we applied the TOC framework to investigate
 65 the robustness of individual patient plans to internal organ motion during treatment and
 66 explore the origin of motion sensitivity. Our goal of this paper is to develop TOC and
 67 AUTOOC as tools in Medical Physics research to relate the details of patient treatment to
 68 clinical endpoints.

69 Three supplemental materials are attached: Supplement A provides the TOC analysis
 70 of a different TCP model; Supplement B provides the TCP model, AUTOOC data for all
 71 patients, an uncertainty analysis of AUTOOC on model parameters, a comparison of clinical
 72 dose-escalated plans and original plans, and an outlier tumor trajectory; and Supplement C
 73 provides a list of acronyms.

74 II. MATERIALS AND METHODS

75 In this section, we first present the TOC framework in the study of tumor motion; then
 76 we introduce the TCP and NTCP models; and lastly, we discuss the details of an example
 77 application with clinical data.

78 A. A TOC framework for studying the effects of tumor motion on treatment 79 efficacy

To evaluate effects of tumor motion, one needs to calculate the motion-blurred dose
 distributions. Since we are not concerned with the effects of image noise, segmentation
 uncertainty, or errors in dose calculation, we can assume the structure boundaries are exact
 and the dose calculation is accurate. Radiation delivered to a structure in the presence of
 tumor motion is the dose accumulated within the structure boundary over time:

$$D(\mathbf{R}) = \int_0^T dt f(\mathcal{T}_t \mathbf{R}, t), \quad (1)$$

80 where D is the accumulated dose distribution, \mathbf{R} is a point in the 3D space, T is the
 81 delivery time of a treatment fraction, f is the dose rate and \mathcal{T}_t is a transformation operator
 82 describing the motion and deformation of the structure at time t . Note that when \mathcal{T}_t is a
 83 unit operator (corresponding to no motion), $D(\mathbf{R})$ is the planned dose distribution, or static
 84 dose distribution $D_s(\mathbf{R})$.

The main effect of organ motion in intensity-modulated radiotherapy is an averaging of the static dose distribution over the path of the motion [43]. If the static dose distribution is not affected much by the internal organ motion, the motion-blurred dose can be calculated by:

$$D(\mathbf{R}) = \frac{1}{T} \int_0^T dt D_s(\mathbf{R} - \Delta\mathbf{R}(t)), \quad (2)$$

85 where $\Delta\mathbf{R}(t)$ is the three-dimensional displacement of the organ at time t . We refer to
 86 this $D(\mathbf{R})$ as the motion-convolved dose. If the tissue of interest is mostly soft tissue and
 87 the organ deformation is not severe, Equation (2) is a good approximation. Otherwise, for
 88 example, if lung tissues and bones exist in the volume of interest, Equation (1) should be
 89 used in the calculation.

The TOC curve is a parametric plot of TCP versus NTCP with the overall dose as a continuous hidden parameter. The overall dose can be varied by changing the beam current or the exposure time. To calculate TCP and NTCP at different overall dose levels, we assume that the clinical dose distribution scales by the same factor at each position \mathbf{R} ,

$$D(\mathbf{R}) = rD_0(\mathbf{R}), \quad (3)$$

90 where $D_0(\mathbf{R})$ is the dose distribution at some reference overall dose and r is the ratio of
 91 the overall dose to the reference dose. As the overall dose increases, TCP and NTCP both
 92 increase and form an ascending TOC curve, as shown in Figure 1.

93 A TOC curve has two nice properties: (1) it can be generated for each dose distribution
 94 $D_0(\mathbf{R})$; and (2) it provides information about treatment efficacy for all possible doses. For
 95 illustration, three target dose levels, 30, 50 and 70 Gy, are marked on the TOC curves in
 96 Figure 1.

97 In current clinical practice, if the treatment dose is escalated, new treatment plans would
 98 be generated to satisfy a different set of dose constraints. We refer to this new plan as a clin-
 99 ical dose-escalated plan. This new treatment plan will produce a new TOC curve. However,
 100 a TOC curve generated by scaling dose of the original plan, as described by Equation (3),
 101 is a good approximation of the family of TOC curves generated from clinical dose-escalated
 102 plans, at least for the purpose of studying the effects of motion. To demonstrate this, we
 103 compare dose scaling and clinical dose escalation in terms of the TOC analysis in the Results
 104 section and Supplement B.

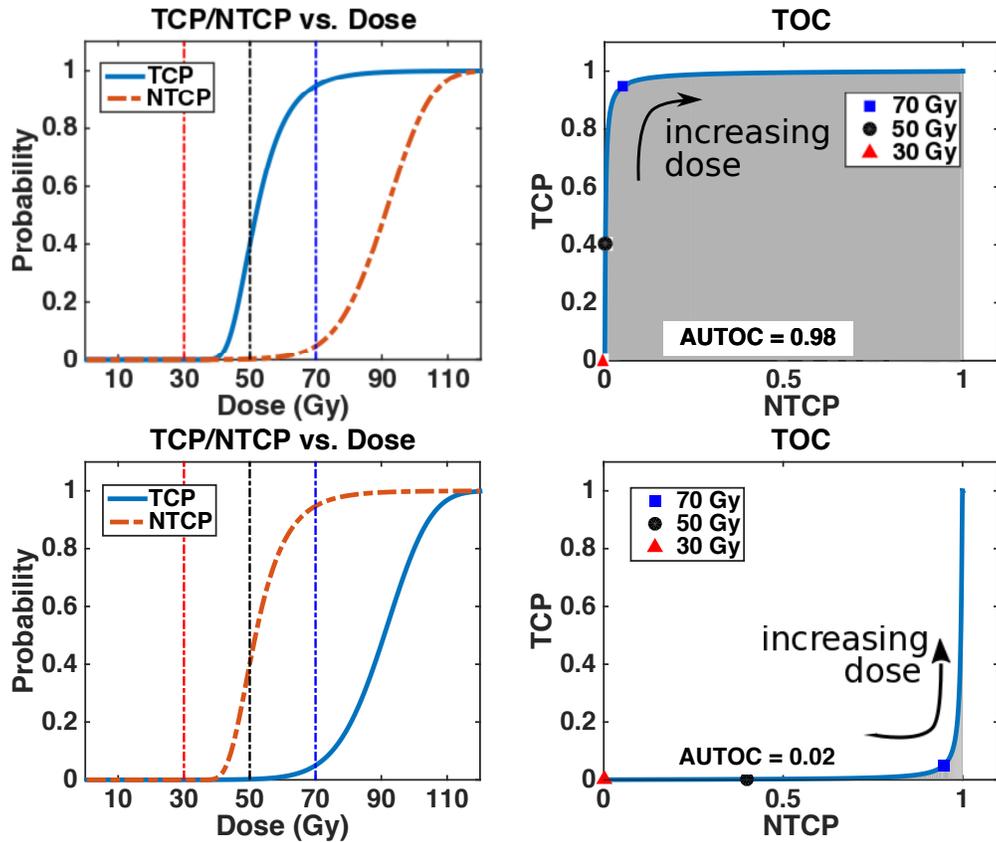


FIG. 1. TCP, NTCP and TOC curve of a good treatment plan (top) and a bad treatment plan (bottom). AUTOC is the area indicated in grey.

105 The therapeutic efficacy of a radiotherapy treatment plan can be evaluated by the AU-
 106 TOC. An ideal treatment plan, which treats the patient without risk of any injuries, has
 107 an AUTOC of 1, as shown in Figure 1 top row. Conversely, an absolutely bad plan, which
 108 damages normal tissue while offering little chance of tumor control, occupies the lower right
 109 corner of the plot and thus has an AUTOC close to 0, as shown in Figure 1 bottom row.

110 Each motion-blurred dose distribution will produce a TOC curve; hence an AUTOC value
 111 can be calculated for each combination of a treatment plan and a motion trajectory.

B. TCP and NTCP models

TCP is a product of the probabilities to control each voxel in the gross tumor volume (GTV)[16]:

$$TCP = \prod_{i=1}^M P(D_i)^{V_i/V_{ref}}, \quad (4)$$

113 where M is the number of voxels, D_i is the dose to the i^{th} voxel, $P(D_i)$ is the local control
 114 probability of the i^{th} voxel, V_i is the volume of the i^{th} voxel, and V_{ref} is the reference volume
 115 of the TCP model [44]. The voxel control probability, $P(D_i)$, can be modeled mechanistically
 116 or empirically. A mechanistic TCP model assumes the following: (1) a tumor consists many
 117 tumor clonogens; (2) curing a tumor requires eradication of all tumor clonogens; and (3) a
 118 mechanistic model can be used to describe the probability of cell death [45]. In contrast,
 119 empirical models take the form of a two-parameter sigmoid-shaped mathematical function
 120 [13].

We briefly summarize a mechanistic model here and introduce an empirical model in Supplement A. The mechanistic model assumes that the number of tumor clonogens follows a Poisson distribution with mean NS , where N is the number of clonogens in the tumor before treatment and S is the fraction of cells that survive radiation treatment. Tumor control occurs when all tumor clonogens have been eradicated:

$$P(D) = e^{-NS(D)}, \quad (5)$$

where D is the dose. The fraction of surviving cells follows

$$S(D) = \int_0^\infty d\alpha p(\alpha) S(D|\alpha) \quad (6)$$

where α describes the radiation sensitivity of cells, $p(\alpha)$ is a probability density function of the radiation sensitivity and $S(D|\alpha)$ is the surviving rate of cells given the radiation sensitivity α . Since cell death is a mechanistic consequence of repair/misrepair of radiation-induced double-strand DNA breaks, $S(D|\alpha)$ often takes the Linear-Quadratic (LQ) form [46]:

$$S(D|\alpha) = \exp[-\alpha D(1 + \frac{D/n}{\alpha/\beta})], \quad (7)$$

121 where $\alpha/\beta = 10$ Gy is generally accepted for tumors and n is the total number of treat-
 122 ment fractions. The tumor heterogeneity model $p(\alpha)$ can be derived from clinical data or
 123 experimental data.

A commonly used NTCP model is a Lyman-Kutcher-Burman (LKB) model [14, 15], which employs an empirical form and attempts to incorporate structural knowledge of the OAR. The model is defined as following:

$$NTCP(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^t dx \exp(-\frac{x^2}{2}). \quad (8)$$

The upper limit of the integration t is defined as

$$t = \frac{EUD - TD_{50}}{m \times TD_{50}}, \quad (9)$$

where m is a model parameter that relates to the inverse slope of the NTCP curve, TD_{50} is the dose that corresponds to a 50% probability of complications, and EUD is the equivalent uniform dose defined as

$$EUD = \left(\sum_i D_i^{1/l} \frac{V_i}{V_{tot}} \right)^l, \quad (10)$$

124 where D_i is the dose in the i^{th} voxel, V_i is the volume of the i^{th} voxel, V_{tot} is the total
 125 volume of the organ, and l is a model parameter related with the structure of the OAR. The
 126 model considers the OAR as many functional subunits (FSUs) organized in series ($l \ll 1$),
 127 in parallel ($l = 1$) or a mixture of both ($0 < l < 1$) [47]. For an organ structured in series,
 128 elimination of any FSUs results in side effects; on the contrary, a parallel organ can tolerate
 129 a larger irradiated volume.

If an NTCP model is derived based on a different fractionation schedule, the biological effective dose (BED) [48] can be used to convert the dose. A commonly used form of BED is given by

$$BED = D(1 + \frac{D/n}{\alpha/\beta}), \quad (11)$$

130 where D is the dose over n fractions. However, the dose conversion should be used with cau-
 131 tion, especially when comparing hypofractionated regimens with conventional fractionation
 132 [49].

133 C. Application of TOC framework in pancreatic SBRT

134 We retrospectively analyzed clinical treatment plans of 25 patients diagnosed with pan-
 135 creatic adenocarcinoma and treated with volumetric-modulated arc therapy (VMAT) at our
 136 institution. Treatment plans were designed to deliver 33 Gy in five fractions. The EclipseTM

137 treatment planning system (Varian Medical Systems, Palo Alto, CA) was used for planning
138 and dose calculation. Treatment plans from these clinical cases were analyzed under an
139 institutional review board (IRB) approved retrospective research protocol.

140 Tumor motion data were collected in a previous study of SBRT for pancreatic cancer [5].
141 Time-resolved tumor positions were estimated from raw cone-beam computed tomography
142 (CBCT) projection images with an automated template-matching algorithm [50–52]. Fidu-
143 cial markers were implanted close to a tumor, and the positions of the fiducial markers were
144 used as surrogates for the tumor location. A total of 91 trajectories of pancreatic tumors
145 were collected from 19 patients. The patients were wearing compression belts at the time
146 of data collection. Each trajectory contained 3D position data over 1 minute at a sampling
147 rate of 15 Hz. The three directions of the trajectories are referred to as superior-inferior
148 (SI), left-right (LR), and anterior-posterior (AP), respectively. For each trajectory, the mag-
149 nitude of motion is defined as the 95% confidence interval (CI) of motion range in the SI
150 direction.

151 For the TCP model, we used the mechanistic model described previously and assumed
152 a model of tumor heterogeneity, $p(\alpha)$, derived from lung SBRT data [53]. The form and
153 parameters of $p(\alpha)$ are provided in Supplement B. For the NTCP model, we used a LKB
154 model derived for pancreatic SBRT by Murphy et. al. [49]. The model predicts Grade II–IV
155 duodenal toxicity [54], including duodenum ulcer, gastrointestinal hemorrhage, duodenum
156 stricture and duodenum perforation for a treatment regimen of 25 Gy in a single fraction.
157 The model parameters are: $TD_{50} = 24.6$ Gy, $m = 0.23$, and $l = 0.12$ [49]. To use this NTCP
158 model, we used BED to convert the dose distribution per five fractions to the equivalent
159 dose obtained using a single-fractionation regimen.

160 We defined the overall dose as the dose prescribed to at least 95% of the planning target
161 volume (PTV). We simulated treatment plans with overall dose ranging 0–120 Gy by
162 scaling the 33-Gy-treatment plans according to Equation (3). To calculate AUTOOC, we
163 extrapolated the TOC curve to a point where NTCP equals to 1 and TCP equals to the
164 TCP value at 120 Gy.

165 We assumed rigid motion of the volume containing the pancreas and the duodenum.
166 The radiation delivered under the presence of a tumor trajectory is calculated according to
167 Equation (2), which averaged the static dose distribution over the tumor trajectory. The
168 accumulated dose under the presence of motion was used to calculate the DVH for the GTV

169 and the duodenum.

170 Firstly, we chose five tumor trajectories to show how TCP, NTCP and TOC curves change
171 with the magnitude of motion. The five tumor trajectories included one ideal trajectory with
172 no motion and four motion trajectories. The four motion trajectories corresponded to the
173 25th, 50th, 75th and 99th percentile of all 91 tumor trajectories in terms of the magnitude of
174 motion, respectively.

175 Secondly, all 91 tumor trajectories were used to study the relation between AUTOC and
176 the magnitude of motion. For each treatment plan and a tumor trajectory combination, a
177 TOC curve and an AUTOC value were calculated. For each treatment plan, 91 AUTOC
178 values were plotted against the motion magnitude.

Thirdly, to approximate the average trend of AUTOC vs. motion, we used a mathematical
motion model to simulate a set of tumor motion trajectories. The motion model, which is
based on lung tumor data [55, 56], assumes the position of the tumor \mathbf{s} as a function of time
 t :

$$\mathbf{s}(t) = \mathbf{s}_0 - \mathbf{S} \cos^{2n} \left(\frac{\pi t}{\tau} - \phi \right), \quad (12)$$

179 where \mathbf{s}_0 is the position of the tumor at exhalation, \mathbf{S} relates to the magnitude of motion, τ
180 is the period of the respiratory cycle, ϕ is the starting phase, and n describes the asymmetry
181 of the motion trajectory. Different trajectories may assume different asymmetry parameter
182 n . Higher values of n means more dwell time in the exhale position. The starting phase
183 ϕ may be different in different directions and this is referred to as hysteresis. We assumed
184 the following parameters: $S_{LR}/S_{SI} = 0.48$, $S_{AP}/S_{SI} = 0.54$ (patient motion data), $\tau =$
185 3.6 seconds, $\phi_{LR} - \phi_{SI} = 0.5$ seconds, $\phi_{AP} - \phi_{SI} = 0.1$ seconds [55] and $n = 3$. To
186 reemphasize, we did not attempt to fit patient motion data into the mathematical model.
187 The motion model was used to approximate the average trend of AUTOC vs. motion.

188 In addition, to examine the effects of uncertainties in the parameters of TCP/NTCP
189 models, we calculated AUTOC for varying model parameters.

190 Furthermore, it is of interest to compare a clinical dose-escalation with dose scaling from
191 the original plan. We replanned three motion-sensitive patients and three motion-robust
192 patients at 50 Gy per five fractions. The 50 Gy was chosen due to the practical reason
193 that many of the dose constraints are clinically unknown for doses much higher than current
194 practices. We compared the new plans and the original plans in terms of TOC curves and
195 AUTOC values.

196 Last but not least, we explored contributing factors to a plan's motion sensitivity. We
197 selected six plans, which consisted of the three most sensitive and the three least sensitive to
198 motion, and compared their dose distributions and tumor volumes. In addition, we compared
199 AUTOC of three-dimensional (3D) motion and one-dimensional (1D) motion, where the 3D
200 motion data were measured from patient and the 1D motion assumed same SI motion as
201 the 3D motion but no motion in the AP direction and the LR direction.

202 **III. RESULTS**

203 **A. Motion sensitivity of treatment plans**

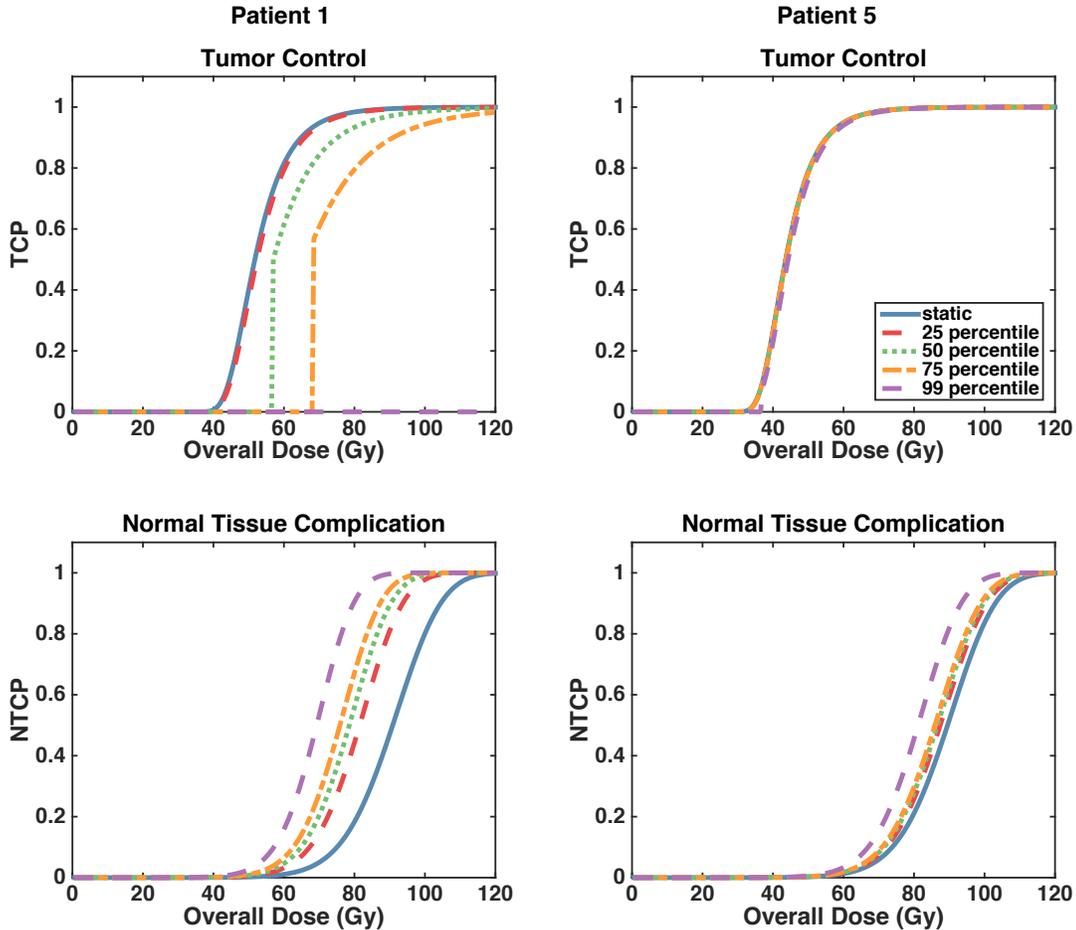


FIG. 2. The effects of motion on TCP and NTCP for Patient 1 (left) and Patient 5 (right). Top row: TCP vs. Overall dose. Bottom row: NTCP vs. Overall dose. Different line colors and styles show four motion trajectories and the ideal scenario of no tumor motion. The four motion trajectories correspond to the 25th, 50th, 75th and 99th percentile of all tumor trajectories in terms of motion magnitude.

204 We plot TCP/NTCP as functions of the overall dose in Figure 2 for two treatment plans.
 205 The 91 tumor trajectories produce 91 TCP plots and 91 NTCP plots for each treatment plan.
 206 In this figure, results of five tumor trajectories, which have been specified in the Methods
 207 section, are presented. The shape of the TCP and NTCP plots change with the magnitude

208 of motion. As the magnitude of motion increases, the shape of the TCP vs. overall dose plots
 209 (top row) changes dramatically for Patient 1 (left column) and barely changes for Patient 5
 210 (right column); the change in NTCP plots (bottom row) of Patient 1 is slightly larger than
 211 that of Patient 5.

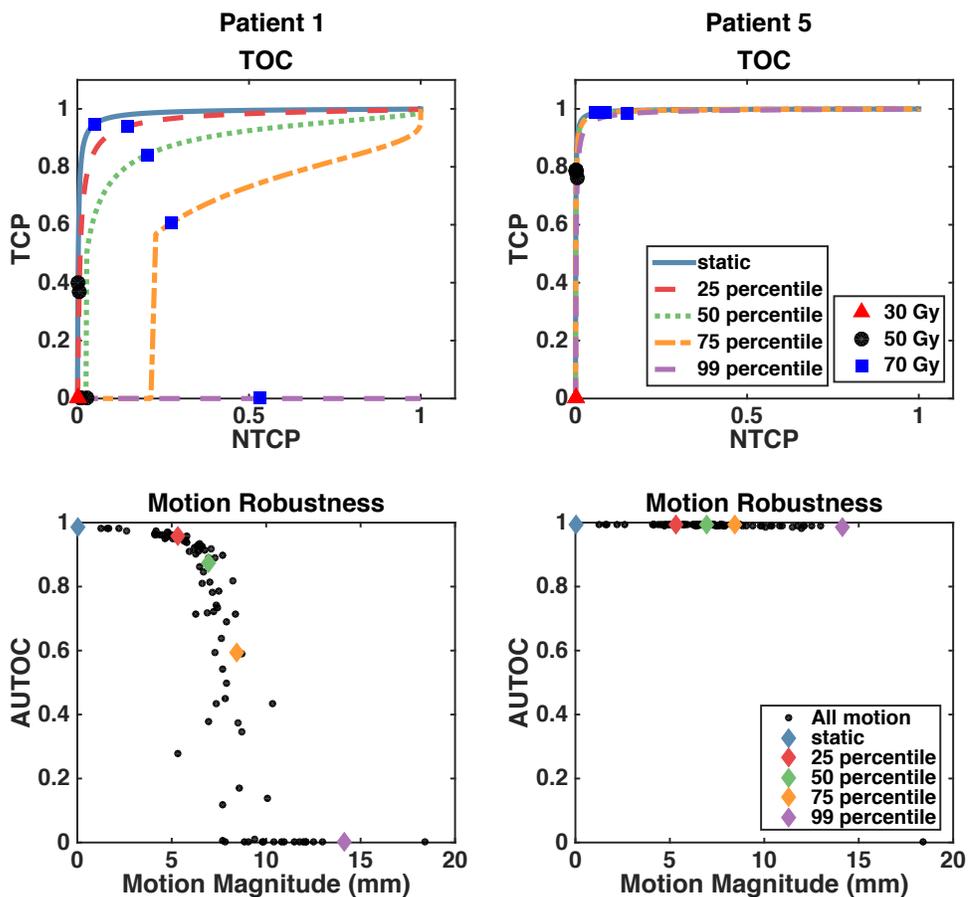


FIG. 3. The effects of motion on TOC curves and AUTOC values for Patient 1 and Patient 5. In the top row, TOC curves of the same five selected trajectories as in Figure 2 are plotted in different line colors and styles. In the bottom row, AUTOC are plotted as a function of motion magnitude. Each black dot is from one tumor trajectory; the diamonds highlights the five selected trajectories. For reference, three target dose levels, 30 Gy, 50 Gy and 70 Gy/5 fractions are indicated on the TOC curves in triangle, circle and square, respectively.

212 To view TCP and NTCP jointly, we combine TCP and NTCP into TOC curves and

213 display the results in the upper row of Figure 3, where the same five tumor trajectories
214 as in Figure 2 are presented. As the magnitude of motion increases, the TOC curves of
215 Patient 1 (left column) shift from the upper left corner (blue, beneficial to the patient) to
216 the lower right corner (purple, harmful to the patient), while the TOC curves of Patient 5
217 (right column) consistently occupy the upper left corner (beneficial to the patient).

218 Each TOC curve provides one AUTOOC value. When all 91 tumor trajectories are consid-
219 ered, there are 91 AUTOOC values. These AUTOOC values are shown by the scatter plot in
220 the lower row of Figure 3, and the five chosen tumor trajectories are indicated in diamonds.
221 The motion magnitude is the 95% CI range in the SI direction. The AUTOOC of Patient 1
222 decreases with increasing motion magnitude, while the AUTOOC of Patient 5 stays close to 1.
223 In other words, the treatment plan of Patient 1 is sensitive to motion, while the treatment
224 plan of Patient 5 is robust to motion.

225

226 For reference, we list conventional motion-sensitivity metrics for the two patients. Since
227 there is a lack of consensus on conventional metrics, three metrics are chosen to our best
228 knowledge: the dose covering 98% of the GTV (D_{98}), the maximum dose covering at least
229 0.1 cm^3 of the duodenum ($D_{0.1cc}$) and the volume of the duodenum that receives more than
230 33 Gy (V_{33}). When no motion is considered, the dose volume metrics for the two patients
231 are: $D_{98} = 33.7 \text{ Gy}$, $V_{33} = 0 \text{ cm}^3$, $D_{0.1cc} = 25.4 \text{ Gy}$ for Patient 1; $D_{98} = 34.2 \text{ Gy}$, $V_{33} = 0 \text{ cm}^3$,
232 and $D_{0.1cc} = 27.3 \text{ Gy}$ for Patient 5. Across all tumor trajectories, D_{98} is $30 \pm 6 \text{ Gy}$ (mean
233 \pm standard deviation) for Patient 1 and $33 \pm 2 \text{ Gy}$ for Patient 5; $D_{0.1cc}$ is $32 \pm 3 \text{ Gy}$ for
234 Patient 1 and $29 \pm 1 \text{ Gy}$ for Patient 5; V_{33} is $0.12 \pm 0.12 \text{ cm}^3$ for Patient 1 and $0.00 \pm 0.01 \text{ cm}^3$
235 for Patient 5. Those values show that the treatment plan of Patient 1 is more sensitive to
236 motion. However, it is hard to combine those physically-based values into one figure of merit
237 that is related to treatment efficacy.

238 As a side reference, three target dose levels, 30 Gy, 50 Gy and 70 Gy per 5 fractions to
239 the PTV, are indicated on the TOC curves in triangle, circle and square, respectively.

240

241 AUTOOC of simulated tumor trajectories can be used to approximate the mean trend of
242 AUTOOC calculated from real patient motion, as shown in Figure 4. The results of all 25
243 patients are presented in Supplement B.

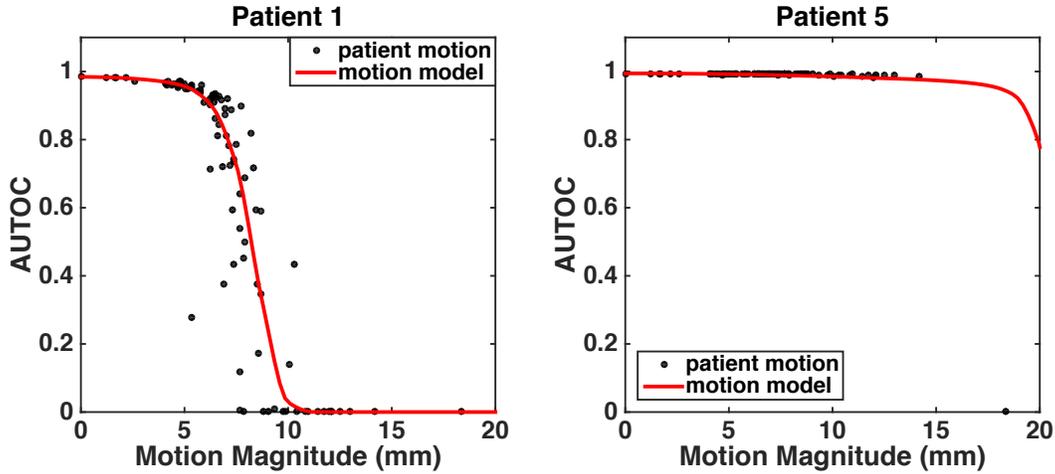


FIG. 4. AUTOC vs. motion magnitude for tumor motion measured from patient (black dots) and a set of simulated tumor trajectories (red line). The simulated tumor trajectories are employed to approximate the mean change of AUTOC with motion for real motion trajectories.

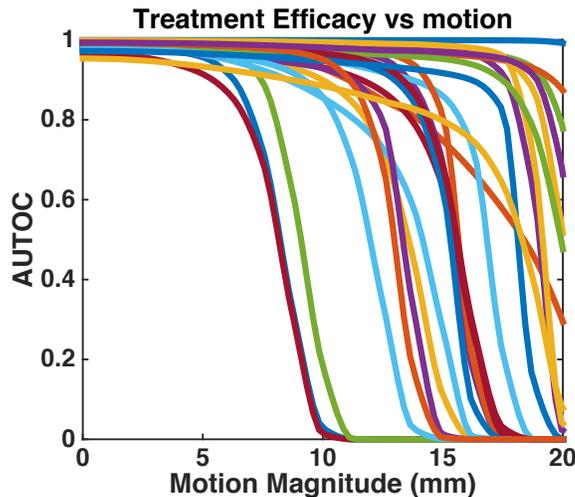


FIG. 5. AUTOC vs. motion magnitude for all 25 patients. The motion magnitude is defined as the 95% CI range in the SI direction. Each line is the AUTOC of one treatment plan, where the AUTOC is calculated based on tumor trajectories generated from the motion model.

244 One can discern the motion sensitivity of different treatment plans by the relationship
 245 between AUTOC and motion magnitude. Figure 5 presents the AUTOC (calculated from
 246 the motion model) as functions of motion magnitude for all 25 treatment plans, where each
 247 line represents one treatment plan. Some plans suffer a sudden decrease in treatment efficacy

248 at a motion magnitude of around 6 mm (95% CI of SI motion). Other plans are robust to
249 tumor motion. In this way, AUTOOC can quantify the motion sensitivity of a given plan.

250 The uncertainties in AUTOOC induced by the uncertainties in parameters in the TCP/NTCP
251 model, including $\bar{\alpha}$, m , l and TD_{50} , are presented in Supplement B. More specifically, $\bar{\alpha}$ is
252 the average radiation sensitivity of the cells in the TCP model; m relates to the inverse slope
253 of the NTCP curve; l describes the organization structure of the FSUs in the OARs; and
254 TD_{50} is the dose that corresponds to 50% of complications. When the model parameters
255 are within the range of uncertainties reported [49, 53], the varying parameters affect the
256 AUTOOC values, but do not drastically influence the shape of the AUTOOC-vs.-motion plots.

257 **B. Dose scaling vs. clinical dose escalation**

258 Clinical dose-escalated plans (replanned) of three motion-robust patients and three
259 motion-sensitive patients are compared to their original plans (the 33 Gy plan) in terms
260 of AUTOOC. We present the results of one patient in this section and the results of the
261 other five patients in Supplement B. If the original plan is robust to motion, the differences
262 between the clinical dose-escalated plan and the original plan are almost negligible in terms
263 of TOC and AUTOOC, as shown in Supplement B. To show a nontrivial case, we present
264 results of one motion-sensitive patient in Figure 6. The left panel shows TOC curves of five
265 selected motion trajectories (same as in Figure 2). The right panel shows AUTOOC values
266 of all motion trajectories.

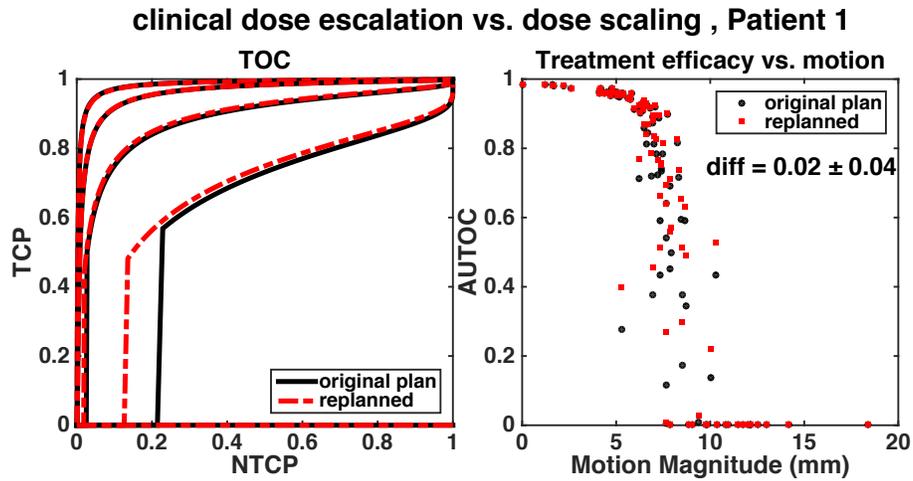


FIG. 6. Comparison of a clinical dose-escalated plan to an original plan in terms of TOC curves and AUTOOC values. The clinical dose-escalated plan is replanned to 50 Gy per 5 fractions. The original plan is 33 Gy per 5 fractions.

267 The difference between the two sets of AUTOOC values is 0.02 ± 0.04 (mean \pm standard
 268 deviation), which is not significantly different from 0. In fact, none of the six cases have
 269 shown significant difference between the new plan and the original plan in terms of AUTOOC.
 270 Therefore, despite the current clinical practice of altering treatment plans when the dose is
 271 escalated, TOC curve with dose scaling is a good surrogate for treatment efficacy over all
 272 doses, at least for the purpose of evaluating the effects of motion.

C. Motion-sensitive vs. motion-robust plans

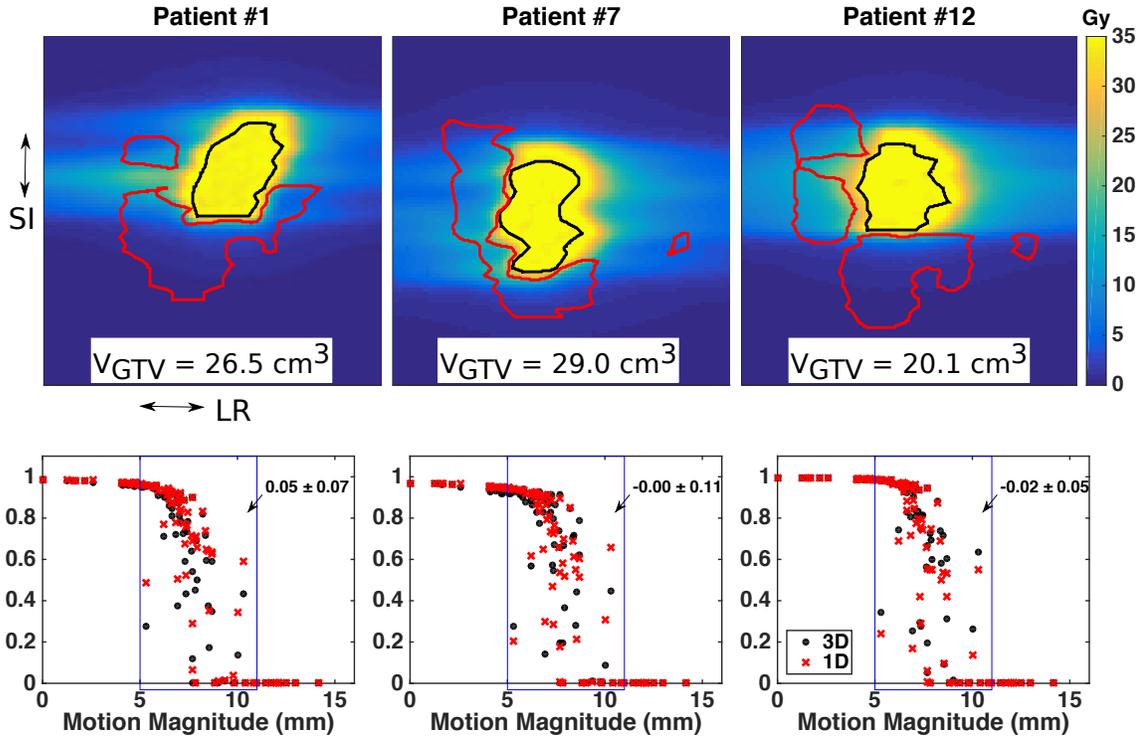


FIG. 7. Dose distribution and AUTOV plots for the three treatment plans that are most sensitive to motion. Each column corresponds to one patient. Top row: one coronal plane slice of the 3D dose distribution in Gy. The slices are chosen to show close proximity between the tumors (black outlines) and the duodenums (red outlines). The size of the slices is $15 \times 15 \text{ cm}^2$. Bottom row: AUTOV vs. motion magnitude for 3D motion (black dots) and 1D SI motion (red crosses). For each plan, the annotation shows the mean and standard deviation of the difference between AUTOV of the 1D motion and 3D motion with magnitude between 5 mm and 11 mm (blue box).

274 The dose distributions of three motion-sensitive plans and three motion-robust plans are
 275 shown in the upper rows of Figure 7 and Figure 8, respectively. For each plan, a 2D coronal-
 276 plane slice of the 3D dose distribution is presented. The slice is chosen at an AP location
 277 where the tumor boundary (black line) is closest to the duodenum boundary (red line). The
 278 orientation of the dose-distribution plots is as follows: the SI direction is along the y axis,
 279 and the LR direction is along the x axis. The motion sensitivity of the plans is shown by the
 280 AUTOV plots in the lower rows of the two figures. In a motion-sensitive plan, the duodenum

281 tends to wrap around the tumor tightly in the SI direction (Patient 1, 7 and 12). When the
 282 tumor is approaching the duodenum from the LR direction (Patient 24), the treatment plan
 283 is robust to tumor motion.

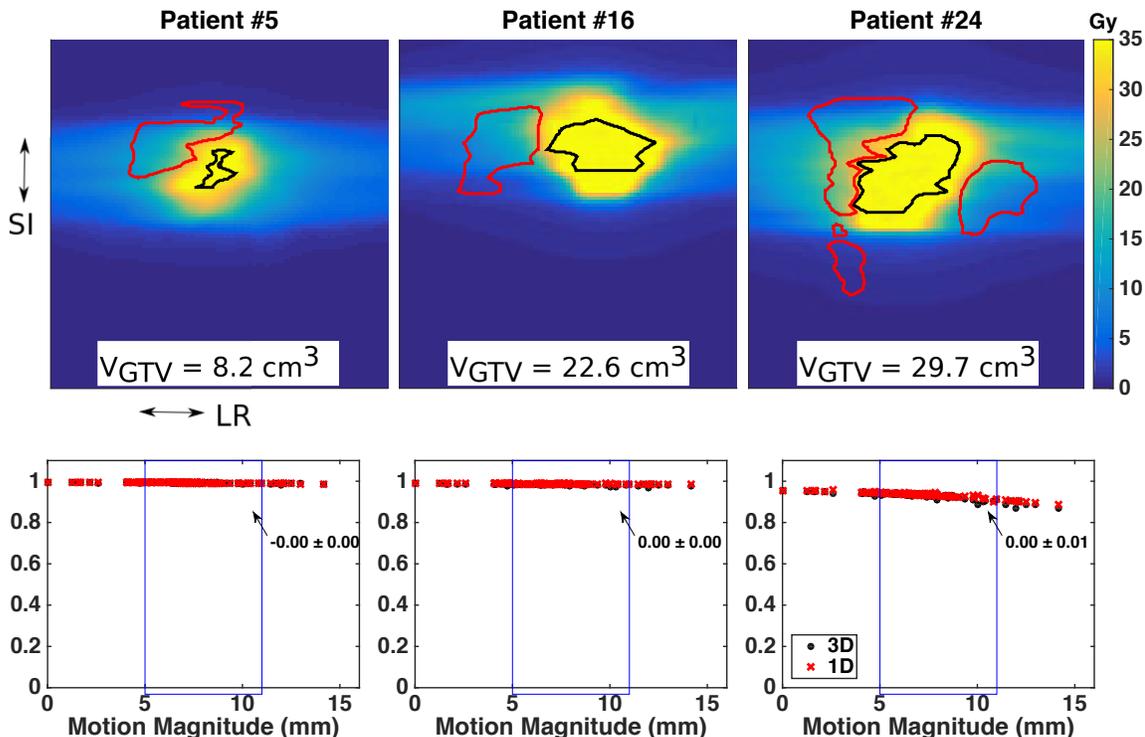


FIG. 8. Dose distribution and AUTOV plots for the three treatment plans that are least sensitive to motion. Details see caption of Figure 7.

284 In the AUTOV plots, results calculated from 3D tumor-motion trajectories measured from
 285 patients are plotted in black dots. AUTOV values calculated from 1D tumor trajectories are
 286 plotted in red crosses. For the motion-robust plans (Figure 8), the AUTOV values of the 1D
 287 motion are very close to that of the 3D motion. For the motion-sensitive plans (Figure 7),
 288 the 1D and 3D results do not match exactly, but they follow the same trend. The range
 289 of motion magnitude where 1D and 3D results are significantly different is 5–11 mm, as
 290 indicated by the blue boxes in the plots. For tumor trajectories with motion magnitude in
 291 this range, the differences between the 1D and 3D AUTOV values are 0.05 ± 0.07 , -0.00 ± 0.11
 292 and -0.02 ± 0.05 for the three motion-sensitive plans and are almost 0 for the three motion-
 293 robust plans. This indicates that the SI motion is the main contributing factor to the
 294 motion-induced changes in AUTOV for the six patients we studied.

295 The tumor volume of the six patients are displayed on the dose maps in Figure 7 and
296 Figure 8. If we define the motion sensitivity of the three motion-sensitive plans as 1 and the
297 three motion-robust plans as 0, the correlation coefficient between the motion sensitivity
298 and the tumor volume is 0.34 with p-value equals to 50%. Based on these six patients, there
299 is no significant correlation between tumor volume and motion sensitivity.

300 In summary, a potential indicator of a motion-sensitive plan is that the tumor is in
301 close proximity to the duodenum in the SI direction. The anisotropic behavior of motion-
302 robustness in direction, or the predilection of the 'SI direction', can be explained by a
303 combination of the following two facts: first, the gradient of radiation field at the tumor-
304 duodenum boundary is larger in the SI direction compared to that in the AP and LR
305 directions as shown in Figure 7 and Figure 8; and second, the magnitude of motion in the
306 SI direction is larger than that in the AP and LR directions [5].

307 IV. DISCUSSION

308 In research studies and clinical trials, the most important endpoints involve the outcomes
309 of the patients being treated. In treatment of cancer, achieving tumor control while min-
310 imizing side effects is the primary goal. Studies that can relate treatment parameters to
311 these outcomes have a greater chance of obtaining clinically significant results. However, in
312 the field of medical physics research, it can be extremely challenging to relate more esoteric
313 characteristics of treatment (e.g. tumor localization accuracy, radiotherapy plan quality,
314 motion management strategies, etc.) to clinical outcomes. The value of AUTOC as a tool
315 for medical physics research is that it can use prior clinical results to distill complex, multi-
316 dimensional data (such as changes in the 3D dose distribution) to a single figure of merit
317 for evaluation. In this way, the true clinical significance of a given research question can be
318 answered.

319 Our results demonstrate the power of AUTOC in quantifying the clinical effects of mo-
320 tion on aggressive treatments such as pancreatic SBRT. It is important to understand the
321 potential risks caused by tumor motion during radiotherapy, as motion affects all tumor
322 sites in the thorax and abdomen. TOC provides an intuitive way to simultaneously quantify
323 the effects of motion on TCP and NTCP. Furthermore, AUTOC provides a quantitative
324 measure of the changes in treatment efficacy under different motion conditions. By relating

325 motion magnitude to AUTO C, we were able to recognize plans that were sensitive to tumor
326 motion. Additionally, we were able to use AUTO C to explore which components of motion
327 were driving these treatment deficiencies, and what aspect of patient anatomy was the main
328 contributor to the motion sensitivity of a given plan.

329 Based on these results, one can imagine clinical scenarios in which the TOC framework
330 is used to tailor an individualized treatment plan for a given patient’s motion profile. In
331 the simplest case, one could derive the maximum amount of motion allowable for a given
332 treatment plan, and use that information to select an appropriate motion management
333 strategy for that patient. This requires further work, because the AUTO C value does not
334 decrease monotonically with motion due to variations in patient motion data, as shown for
335 Patient 1 in Figure 4 (black dots). A naive way to calculate allowable motion is to set
336 an arbitrary threshold on AUTO C and calculate the maximum magnitude of motion that
337 ensures AUTO C being larger than the threshold. The threshold can be chosen based either
338 on all tumor trajectories (black dots in Figure 4) or the mean trend (red line in Figure 4).
339 A more sophisticated method to select the optimized threshold involves: (1) an ROC curve
340 that plots the true positive rate against the false positive rate at various AUTO C threshold
341 settings and (2) calculating optimal threshold value based on the cost of misclassification of
342 a tumor trajectory on whether it is safe for the treatment or not. How to optimally select
343 a threshold on AUTO C is an interesting topic for future work.

344 Another approach could be to identify plans that need replanning using robust opti-
345 mization, which incorporates motion information into the IMRT optimization process [57].
346 Building on this, it may be possible to include TOC framework in the plan optimization
347 process, and build a treatment plan that is robust to motion. For example, measures, such as
348 AUTO C values at a given motion magnitude or the areas under the AUTO C-motion curve,
349 may serve as guides to optimize treatment plans. Going even further, one could perform a
350 detailed motion evaluation at the time of simulation, and use this information to design an
351 individualized treatment fractionation which achieves TCP values as high as possible. To
352 achieve these goals, further work is needed to understand exactly which factors cause a plan
353 to be sensitive or robust to motion.

354 Other applications of the TOC analysis include: evaluating segmentation algorithms,
355 comparing motion-management techniques, assessing the effects of using molecular imaging
356 in therapy planning, evaluating and optimizing internal radiotherapy with the sodium iodide

357 symporter [30]. A computational framework which employs AUTO C to guide optimization of
358 different components of the treatment-planning process has been developed recently by Dolly
359 et. al. [32]. With this framework, one can optimize parameters in pre-treatment imaging
360 such as imaging dose, compare segmentation algorithms and evaluate plan optimization
361 algorithms.

362 The TOC analysis has to be applied with appropriate caution, because TOC curves
363 constructed from the TCP and the NTCP dose-response curves are subject to moderately
364 large uncertainties. This is because the TCP and the NTCP models are estimated from
365 limited amounts of clinical data focused on the relatively low-dose range. Further discussions
366 on uncertainties in TOC curves and precautions to take when using the curves can be
367 found in Metz et. al. [26]. We examined uncertainties due to varying model parameters in
368 Supplement B, the results show that there are uncertainties in the AUTO C values, but the
369 trend of the AUTO C-vs.-motion plot does not change much. Furthermore, fractionation
370 schedule may introduce uncertainties to the TOC analysis. The TCP/NTCP models may be
371 derived based on different fractionation schedules; uncertainties in converting doses between
372 different fractionation schemes may affect the TOC analysis.

373 Dose scaling is used in the TOC analysis to generate TCP and NTCP at varying overall
374 dose levels. When compared in terms of AUTO C, the clinical dose-escalated plans are not
375 significantly different from the original plans. Dose scaling is reasonable at least for the
376 purpose of evaluating the effects of motion. Moreover, in emerging research of personalized-
377 dose prescription, there is a renewed interest in changing the overall dose after a treatment
378 plan has been generated [33, 58–61]. If such a treatment regimen is used, a TOC curve, with
379 the overall dose as the hidden variable, provides a full picture of the trade-offs between the
380 risks and the benefits, independent of the dose level.

381 An important limitation of our work is that we used pancreatic data but did not use a
382 pancreatic SBRT TCP model. SBRT is emerging as an attractive therapeutic option for
383 patients with pancreatic tumors. However, since higher doses per fraction are only beginning
384 to see widespread use, there is a lack of quality clinical data relating dose distributions and
385 outcomes for these high-dose treatments. As a result, there is little consensus to date on
386 TCP models of pancreatic SBRT. TCP models of high-dose treatments to the lung, brain,
387 head and neck, and liver have been published recently [22, 53, 62]. Since these models
388 were based on similar dose fractionation schemes as pancreatic SBRT, they might provide

389 reasonable estimates for the TCP in pancreatic SBRT. Therefore, TCP models based on
390 lung and liver SBRT data (Supplement A) were considered to approximate local control of
391 pancreatic SBRT. Future clinical trials of pancreatic SBRT will provide better guidance in
392 this regard.

393 Another limitation is that we assumed rigid motion of the pancreas and the duodenum.
394 The pancreas can undergo deformation up to 5 mm during respiration, yet on average the
395 tumor borders are deformed by only 1—2 mm [41]. The deformation is small compared to
396 the typical magnitude of pancreatic motion (1—2 cm) [5]. One study [63] compared rigid and
397 deformable dose accumulation in liver SBRT and found that the rigid dose accumulation
398 led to dose errors averaging less than 1% of the prescription dose for the tumor and the
399 normal tissue (ranging from -5.1% — 8.3%). With these data, we think that rigid motion is
400 a reasonable approximation. However, future work on this topic may include the effects of
401 deformation (perhaps using intrafraction images obtained from MR-equipped linacs).

402 V. CONCLUSIONS

403 In conclusion, we presented TOC as a tool and AUTOOC as a figure of merit to objectively
404 quantify the effects of motion on treatment efficacy. We demonstrated the application of
405 TOC and AUTOOC with clinical data while studying the motion sensitivity of pancreatic
406 SBRT treatment plans. We were able to identify motion-sensitive plans and explore the
407 cause of the motion sensitivity. Furthermore, we explored the uncertainties in the TOC
408 analysis.

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415 **DISCLOSURE OF CONFLICTS OF INTEREST**

416 Drs. Jones and Miften have filed a provisional patent application for the fiducial marker
417 tracking technique used in the collection of tumor motion data. Other authors have no
418 relevant conflicts of interest to disclose.

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