

1 The Impact of Sampling Frequency on Ground Reaction Force Variables

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11 **Abstract**

12 New portable and low-cost technologies for assessing limb loading may be useful in non-
13 laboratory environments, but have relatively low sampling frequencies. The lowest
14 recommended sampling frequency for impact kinetics has not been investigated. The purpose of
15 this study was to determine the effect of sampling frequency on metrics of impact kinetics during
16 landing, walking, and running. This was a retrospective analysis of bilateral drop vertical jumps,
17 unilateral drop landings, treadmill running, and flat, inclined, and declined treadmill walking.
18 Landing data were collected at 1920 Hz while walking and running data were collected at 1440
19 Hz. Impact kinetics were computed at the highest possible sampling frequency, and then data
20 were continuously down-sampled to determine the impact on the following computed metrics:
21 peak impact force, average LR, and impulse. The minimum sampling frequency to compute each
22 outcome with 90%, 95%, and 99.5% accuracy when compared to the original sampling
23 frequency were determined. To achieve 90% of the true value of impact force, a sampling
24 frequency of 180Hz was needed for running, 62 Hz for bilateral landing, and 48 Hz for
25 remaining tasks. For average LR, a sampling frequency of 1440 Hz was need for running, 63 Hz
26 for inclined walking, 192 Hz for bilateral landing, and 48 Hz for the remaining tasks. For
27 impulse, 48 Hz was required for all tasks. The results of this study provide future researchers
28 with a guide for selecting the sampling frequency required to accurately assess impact kinetics
29 during walking, landing, or running.

30

31 **Keywords:** Data processing; biomechanics; walking; running; landing

32 **Introduction**

33 Assessing impact kinetics during everyday and athletic movements can provide
34 information about an individual's risk for sustaining a musculoskeletal injury. For example,
35 increased peak vertical impact force during landing is prospectively associated with an increased
36 incidence of anterior cruciate ligament (ACL) injuries in young female athletes (Hewett et al.,
37 2005; Leppänen et al., 2017). Increased loading rate (LR) is associated with tibial stress fractures
38 in recreational runners (Milner et al., 2006; Zadpoor and Nikooyan, 2011). Additionally,
39 decreased vertical ground reaction force GRF peaks and impulse during walking have been
40 reported in total hip arthroplasty and knee osteoarthritis patients, respectively (Mccrory et al.,
41 2001; Wiik et al., 2017). To measure GRF researchers often use embedded force plates,
42 considered the gold standard for such studies. However, these devices are not widely used in
43 non-research settings due to expense and lack of portability. Portable force plates and force-
44 sensing insoles are more affordable and practical for use in non-research settings and have also
45 become more popular among researchers, but these devices often utilize lower sampling rates
46 than those of lab-grade embedded force plates. With a low sampling rate, there is a concern that
47 critical information will be lost and that the accuracy of impact kinetic outcomes will degrade.

48 Previous studies have determined that propulsive kinetic outcomes could be accurately
49 assessed when sampling as low as 200 Hz (Hori et al., 2009) during the jumping phase of a
50 countermovement jump. However, we currently lack an understanding of the relationship
51 between sampling rate and the accuracy of kinetic outcomes for other tasks such as walking,
52 running and landing. Because portable force-measuring devices employ various maximum
53 sampling frequencies, it would be helpful for researchers and clinicians to know the lowest
54 sampling frequency that can be used to accurately assess a desired outcome for a particular

55 movement task. Such information would provide quantitative criteria for rejection of devices that
56 do not meet the minimum frequency threshold. Therefore, the purpose of this study was to
57 determine the effect of sampling frequency on impact kinetic outcomes during landing, walking,
58 and running tasks.

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60 **Methods**

61 *Participants*

62 This study was a secondary analysis of data collected during three previous studies. The
63 first consisted of thirty participants who completed a landing protocol (Peebles et al., 2018); the
64 second consisted of twenty participants who completed a treadmill running protocol (Peebles et
65 al., 2021); and the third consisted of twenty participants who completed a waking protocol
66 (Renner et al., 2019), Table 1.

67 For all studies, the participants met the following inclusion criteria: 1) between 18 and 30
68 years old, 2) recreationally active, defined as participating in physical activity at least three times
69 per week for at least thirty minutes, 3) injury free, defined as not having had an injury in the
70 previous three months and not having any current pain that impacted mobility, and 4) never had
71 a major lower extremity injury or surgery. These studies were approved by the Virginia Tech
72 Institutional Review Board, and participants signed forms that gave consent for both the primary
73 studies and secondary data analysis.

74 *Procedure*

75 The landing protocol consisted of seven bilateral drop vertical jumps and seven unilateral
76 drop landings on each limb. For the bilateral landing task, participants stood on a box (31 cm),
77 jumped forward toward a target placed half their body height away from the box, completed a

78 bilateral landing, and then immediately jumped vertically as high as possible (Bell et al., 2014;
79 Peebles et al., 2021). For the unilateral drop landing task, participants stood on one foot on top of
80 the box, dropped straight off, and landed on the ground with the same foot (Ithurnburn et al.,
81 2017; Peebles et al., 2021). Impact kinetics were measured throughout each landing at a
82 sampling rate of 1920 Hz using two embedded force plates (AMTI, Watertown, Massachusetts).

83 The treadmill running protocol consisted of running on a fore-aft split-belt instrumented
84 treadmill (AMTI, Watertown, MA) for one minute using a sampling rate of 1440 Hz (Peebles et
85 al., 2021). Participants walked for 1 minute at a comfortable walking speed on the same
86 instrumented treadmill at 0% incline, 10% incline, and a 10% decline. Participants ran and
87 walked at their preferred speeds (Dingwell and Marin, 2006). Data from six participants in the
88 running study did not have clearly defined impact peaks and were excluded from LR
89 calculations. The average self-selected running speed was 2.72 ± 0.47 m/s. The self-selected
90 walking speed during the level walking was 1.23 ± 0.26 m/s, for declined it was 1.22 ± 0.33 m/s,
91 and for inclined the average speed was 1.15 ± 0.25 m/s.

92 *Analysis*

93 All data analysis was performed using unfiltered data in Matlab (MathWorks Inc.,
94 Nantucket, Massachusetts). During the bilateral landing task, the vertical GRF was analyzed for
95 the first landing for each trial (Peebles et al., 2018). The first 200 ms of each unilateral landing
96 trial were used for data analysis. In the running trials, each step during a ten-second window was
97 analyzed, and ten steps were analyzed for each walking condition. Peak force, LR, and impulse
98 were calculated for each task. For bilateral landing, peak impact force was calculated as the peak
99 force that occurred in the first 30% of the ground contact phase (time between initial contact and
100 toe-off) (Peebles et al., 2018). For unilateral landing, running, and walking, the peak impact

101 force was determined as the first peak in force that occurred following initial contact (Milner et
102 al., 2006). For all tasks initial contact was identified when the force exceeded 25 N (Peebles et
103 al., 2018). For walking and running, toe-off was identified as the timepoint when the force
104 dropped below 25N for 5 frames of data.

105 Average LR was computed as the peak impact force divided by the time between initial
106 contact and peak impact force (Peebles et al., 2018) for both landing, and all walking conditions.
107 For the running task, both the peak LR and average LR were computed using the linear portion
108 of the force-time profile, which was identified between 20% and 80% of the time between initial
109 contact and peak impact force (Milner et al., 2006). Finally, impulse was computed as the area
110 under the force-time profile during the ground contact phase for bilateral landing, running, and
111 walking (Peebles et al., 2018; Renner et al., 2019), and the first 200 ms following initial ground
112 contact for unilateral landing (Peebles et al., 2018).

113 All study outcomes were computed using the raw, unfiltered force-plate data, which were
114 considered as the ‘true values’ in the analysis. Then, the force plate data were consecutively
115 downsampled until a sampling frequency of 48 Hz. This reduction was conducted by keeping
116 every 2nd, 3rd, 4th, etc. data points, creating new sampling frequency datasets (Hori et al.,
117 2009). Outcomes were computed at each stage of the downsampling process (Figure 1). A
118 detailed list of sampling frequencies is available as supplemental material.

119 The error was computed at each sampling frequency as the percent difference relative to
120 the true value for each trial, and then averaged across trials for each participant. The sampling
121 frequency required to achieve 99.5%, 95% and 90% of the true value was then identified. The
122 outcomes from the downsampled data were plotted against the modeled sampling frequency
123 (Figure 2). Additionally, an intraclass correlation coefficient (ICC) was calculated using the

124 norm-referenced reliability calculation (ICC(C,1) in Matlab) for each task and variable of
125 interest. For example, if the original sampling frequency was 1440 Hz the first ICC was
126 calculated between 1440 Hz and 720 Hz, then the ICC was calculated between 1440 Hz and 480
127 Hz and so on until an ICC was calculated between 1440 Hz and 48 Hz. An ICC above 0.90 was
128 considered excellent, 0.75-0.89 good, 0.50-0.74 moderate and below 0.50 poor (Koo & Li,
129 2016).

130 **Results**

131 The true values for each kinetic outcome are presented in Table 2. The minimum
132 recommended frequency to reach 90%, 95%, and 99.5% of the true value for each outcome is
133 reported in Table 3. Across all conditions, LR was the most sensitive outcome to decreases in
134 sampling frequency, and impulse was least affected. In general, running and bilateral landing
135 were the movement conditions most sensitive to decreases in sampling frequency and walking
136 and unilateral landing were least sensitive.

137 The peak GRF and impulse ICC analysis indicated excellent correlations with peak GRF
138 with ICC values ≥ 0.93 and impulse ICC values ≥ 0.99 for all tasks and sampling frequencies. LR
139 ICC values had greater variance between tasks. In flat walking, the ICC dropped below 0.90 at
140 48Hz (0.88), whereas inclined walking, declined walking, and unilateral landing LR remained in
141 the excellent category for all sampling rates (>0.99). The ICC values for the average LR in
142 running dropped to 0.89 at 103 Hz, 0.75 at 76 Hz, and 0.6 at 48 Hz. The ICC for peak LR during
143 running decreased quicker, with an ICC of 0.88 at 180 Hz, 0.74 at 80 Hz, and 0.55 at 48 Hz.
144 Finally, bilateral landing ICC values dropped to 0.89 at 77 Hz, 0.72 at 56.5 Hz, and 0.63 at 48
145 Hz. The ICC values for each sampling frequency tested can be found in the supplemental
146 materials.

147 **Discussion**

148 The present study determined the impact of sampling frequency on peak impact force,
149 LR, and impulse during a bilateral drop vertical jump, unilateral drop landing, as well as
150 treadmill running and walking. The study results indicate that impulse was the least affected by
151 sampling frequency and can be determined within 95% of the true value using a sampling
152 frequency as low as 100 Hz. LR was the most sensitive to sampling frequency, which was likely
153 the result of compounding the variance in the magnitude and timing of peak impact force, as well
154 as the variance in the timing of initial contact. These findings are consistent with previous work,
155 which found force-sensing shoe insoles (100 Hz) can accurately measure impulse during landing
156 and running, but are less accurate when measuring LR (Peebles et al., 2018). Peak force and LR
157 were sensitive to sampling frequency during running, which was likely due to the impact peak
158 occurring very quickly during running and disappearing at lower frequencies.

159 One limitation of the present study was the choice to not filter the data. Force-plate data
160 are often filtered (Bell et al., 2014; Hewett et al., 2005; Leppänen et al., 2017; Renner et al.,
161 2018), which would likely affect the magnitude and timing of each study outcome. Additionally,
162 it should be noted that this study analyzed the impact of down-sampling on force-plate data,
163 which represent the force between the sole of the shoe and the ground. Many of the newer and
164 more mobile technologies are in-shoe insoles, which record the force between the foot and the
165 shoe. Owing to the material response of the sole of the shoe, the exact timing and magnitude of
166 forces recorded from these two locations must be different in principle. However, the values are
167 likely to be similar enough that our conclusions about down-sampling should be similarly
168 applicable.

169 Previous research on the impact of sampling frequency has been conducted on tracking
170 center of pressure (Koltermann et al., 2018) and GRF metrics during a counter movement jump
171 (Hori et al., 2009). Both studies advise a sampling frequency of at least 100 Hz, with Hori et al.
172 suggesting 200 Hz (Hori et al., 2009; Koltermann et al., 2018). This study indicates that a
173 sampling rate of 100 Hz will be able to calculate the peak force and impulse within 0.5% of the
174 true value and LR within 5% for walking. The more dynamic tasks have a wider range of
175 minimum sampling rates. For running, a sampling rate of 1440 Hz should be used when
176 assessing peak impact force and LR. A sampling rate of 500 Hz was sufficient for peak impact
177 force and impulse during landing; however, a greater sampling rate was needed to reliably
178 quantify LR. These results indicate that technology with lower sampling rates could be suitable
179 for lower impact tasks such as walking, but investigators should consider the potential difference
180 in metrics for more dynamic tasks.

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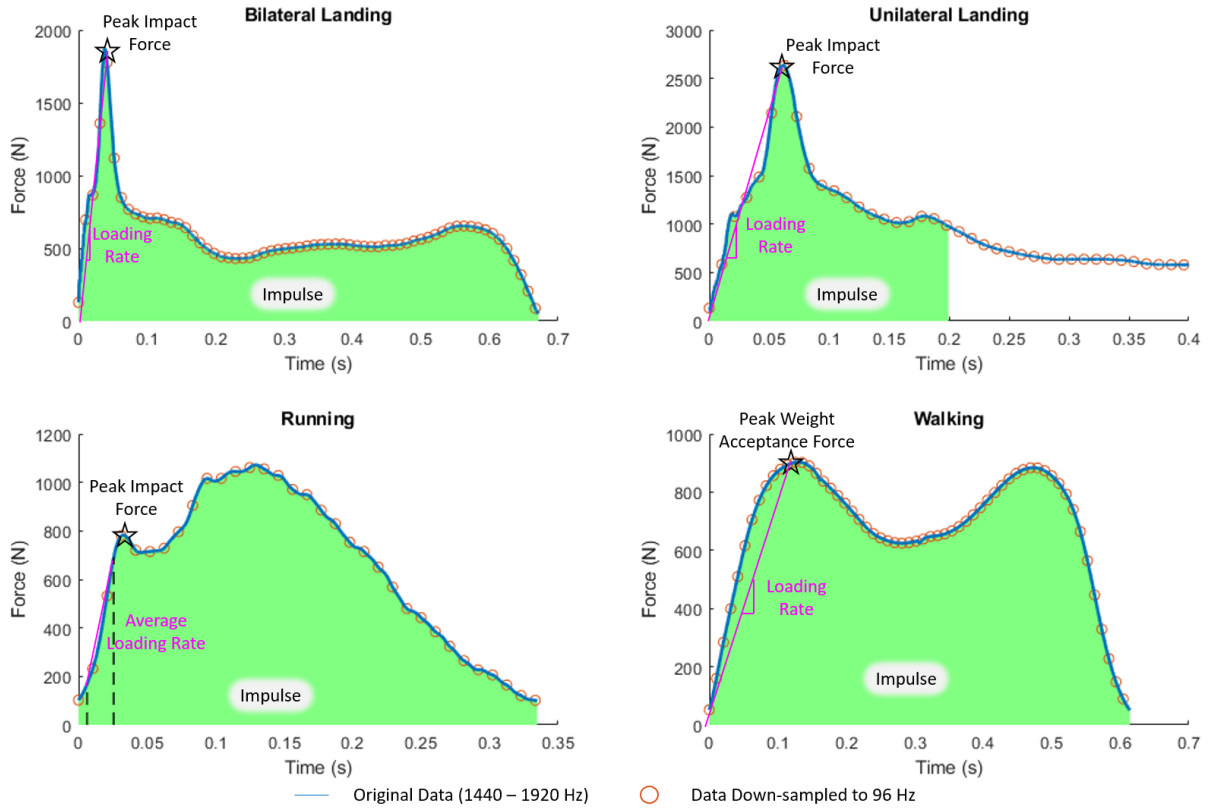
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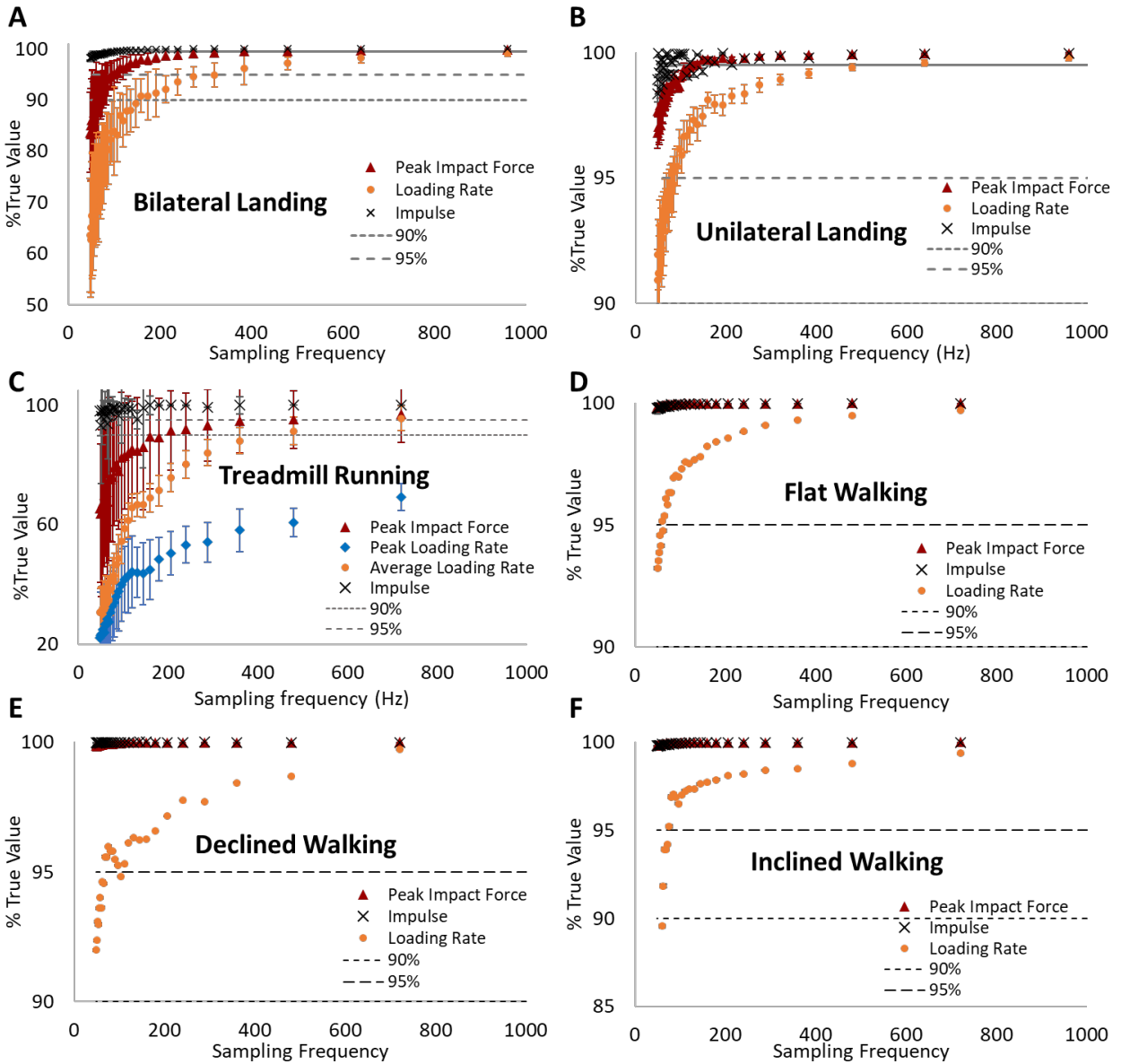
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236 **Figure 1:** Representative data for each movement and outcome included in the present study.
 237 The original data (recorded at 1440-1920 Hz) are indicated with a thick blue line, and a
 238 representative downsampled dataset (recorded at 96 Hz) is shown with orange circles.
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241 **Figure 2:** Relationship between sampling frequency and the true value for each outcome across
 242 A) bilateral landing, B) unilateral landing, C) treadmill running, D) flat treadmill walking, E)
 243 declined treadmill walking, and F) inclined treadmill walking. All error bars represent one
 244 standard deviation across study participants; in some cases, the bar cannot be seen because the
 245 standard deviation is smaller than the marker.
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250 **Table 1:** Participant demographics for three studies that provided the original data to down-
251 sample.

	Landing Study		Running Study		Walking Study	
	Male n =15	Female n =15	Male n =10	Female n =10	Male n =11	Female n =9
Age (years)	23.60 ± 2.20	22.93 ± 3.08	21.50 ± 2.27	22.20 ± 2.53	21.64 ± 2.62	22.89 ± 3.14
Height (m)	1.79 ± 0.07	1.72 ± 0.05	1.81 ± 0.06	1.69 ± 0.06	1.79 ± 0.08	1.68 ± 0.05
Weight (kg)	77.19 ± 15.11	63.46 ± 8.92	77.34 ± 11.62	63.56 ± 9.76	73.39 ± 8.95	67.80 ± 13.88

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254 **Table 2:** True values for the kinetic outcome variables for each task. Values are normalized to
 255 body weight (BW) at 1920 Hz for the landing tasks and 1440 Hz for walking and running tasks.
 256 The running task lists both the average LR and the peak LR and the other tasks report the
 257 average LR.

	Impact Force (BW)	LR (BW/s)	Impulse (BW*s)
Bilateral Landing	2.25 ± 0.56	64.29 ± 30.53	0.52 ± 0.06
Unilateral Landing	3.99 ± 0.61	78.46 ± 16.74	0.42 ± 0.04
Treadmill Running	1.560 ± 0.26	Peak: 169.30 ± 40.29 Ave: 64.39 ± 20.20	0.39 ± 0.07
Flat Walking	1.10 ± 0.09	6.37 ± 1.97	0.57 ± 0.05
Declined Walking	1.27 ± 0.16	9.54 ± 3.00	0.52 ± 0.04
Inclined Walking	1.02 ± 0.06	5.19 ± 1.80	0.58 ± 0.05

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260 **Table 3:** Recommended minimum sampling frequency (in Hz) to achieve 90%, 95%, and 99.5%
 261 accuracy, relative to the True Value (TV), which was obtained at 1920 Hz for landing and 1440
 262 Hz for treadmill running.

	90% TV	95% TV	99.5% TV
Bilateral Landing			
Peak Impact Force	62	96	384
Average LR	192	384	1920
Impulse	48	48	106
Unilateral Landing			
Peak Impact Force	48	48	137
Average LR	48	87	640
Impulse	48	48	148
Treadmill Running			
Peak Impact Force	180	480	1440
Peak LR	1440	1440	1440
Average LR	480	720	1440
Impulse	48	110	240
Flat Walking			
Peak Impact Force	48	48	48
Average LR	60	76	720
Impulse	48	48	48
Declined Walking			
Peak Impact Force	48	48	48
Average LR	48	111	720
Impulse	48	48	48
Inclined Walking			
Peak Impact Force	48	48	48
Average LR	63	76	720
Impulse	48	48	48

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Supplemental Table 1: Detailed list of sampling frequencies for each iteration for the bilateral and unilateral landing tasks (Landing Tasks) and for walking and running data (Gait).

Iteration	Landing Tasks	Gait
1 (Original)	1920	1440
2	960.0	720.0
3	640.0	480.0
4	480.0	360.0
5	384.0	288.0
6	320.0	240.0
7	274.3	205.7
8	240.0	180.0
9	213.3	160.0
10	192.0	144.0
11	174.5	130.9
12	160.0	120.0
13	147.7	110.8
14	137.1	102.9
15	128.0	96.0
16	120.0	90.0
17	112.9	84.7
18	106.7	80.0
19	101.1	75.8
20	96.0	72.0
21	91.4	68.6
22	87.3	65.5
23	83.5	62.6
24	80.0	60.0
25	76.8	57.6
26	73.8	55.4
27	71.1	53.3
28	68.6	51.4
29	66.2	49.7
30	64.0	48.0
31	61.9	
32	60.0	
33	58.2	
34	56.5	
35	54.9	
36	53.3	
37	51.9	
38	50.5	
39	49.2	
40	48.0	

268 **Supplemental Table 2:** Exact ICC values for each sampling frequency for all walking tasks and
 269 running. Abbreviations: Peak GRF (GRF), Impulse (I), LR (LR), Average LR (LR-Avg), Peak
 270 LR (LR-Pk).

	Flat Walking			Inclined Walking			Declined Walking			Running			
	GRF	I	LR	GRF	I	LR	GRF	I	LR	GRF	I	LR-Avg	LR-Pk
720	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.97	1.00	1.00	0.98
480	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.96	1.00	0.99	0.96
360	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.96	1.00	0.98	0.96
288	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.94	0.99	0.96	0.96
240	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.92	1.00	0.96	0.94
205.7	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.92	1.00	0.95	0.94
180	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.90	1.00	0.93	0.92
160	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.91	1.00	0.92	0.87
144	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.83	0.99	0.87	0.88
130.9	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.80	0.99	0.87	0.89
120	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.83	0.99	0.89	0.89
110.8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.84	0.99	0.78	0.87
102.9	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.80	0.99	0.76	0.86
96	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.81	0.99	0.73	0.83
90	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.74	0.82	0.63	0.73
84.7	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.99	0.77	0.99	0.59	0.72
80	1.00	1.00	1.00	1.00	1.00	0.99	1.00	1.00	0.99	0.77	1.00	0.57	0.70
75.8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.99	0.74	1.00	0.42	0.58
72	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0.99	0.73	0.99	0.44	0.58
68.6	1.00	1.00	1.00	1.00	1.00	0.99	1.00	1.00	0.99	0.72	0.99	0.31	0.44
65.5	1.00	1.00	0.99	1.00	1.00	0.99	1.00	1.00	0.99	0.65	0.82	0.36	0.46
62.6	1.00	1.00	0.99	1.00	1.00	0.99	1.00	1.00	0.99	0.69	0.81	0.29	0.46
60	1.00	1.00	0.99	1.00	1.00	0.99	1.00	1.00	1.00	0.71	0.99	0.32	0.46
57.6	1.00	1.00	0.99	1.00	1.00	0.99	1.00	1.00	0.99	0.73	0.96	0.19	0.27
55.4	1.00	1.00	0.99	1.00	1.00	0.99	1.00	1.00	0.99	0.69	0.99	0.33	0.43
53.3	1.00	1.00	0.99	1.00	1.00	0.99	1.00	1.00	0.99	0.67	0.99	0.17	0.28
51.4	1.00	1.00	0.99	1.00	1.00	0.99	1.00	1.00	0.99	0.67	0.81	0.25	0.37
49.7	1.00	1.00	0.99	1.00	1.00	0.99	1.00	1.00	0.99	0.67	0.81	0.33	0.48
48	1.00	1.00	0.88	1.00	1.00	0.99	1.00	1.00	0.99	0.72	0.99	0.17	0.27

Key:	Excellent (≥ 0.90)	Good (0.75-0.89)	Moderate (0.50-.74)	Poor (< 0.50)
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Supplemental Table 3: Exact ICC values for each sampling frequency for bilateral and unilateral landing tasks. Abbreviations: Peak GRF (GRF), Impulse (I), LR (LR).

	Bilateral Landing			Unilateral Landing		
	GRF	I	LR	GRF	I	LR
960	1.00	1.00	1.00	1.00	1.00	0.97
640	1.00	1.00	1.00	1.00	1.00	0.97
480	1.00	1.00	1.00	1.00	1.00	0.98
384	1.00	1.00	0.99	1.00	1.00	0.99
320	1.00	1.00	0.99	1.00	1.00	0.99
274.3	1.00	1.00	1.00	1.00	1.00	0.99
240	1.00	1.00	0.99	1.00	1.00	0.98
213.3	1.00	1.00	0.99	1.00	1.00	0.99
192	1.00	1.00	0.97	1.00	1.00	0.99
174.5	1.00	1.00	0.97	1.00	1.00	0.99
160	1.00	1.00	0.99	1.00	1.00	0.98
147.7	1.00	1.00	0.98	1.00	1.00	0.99
137.1	1.00	1.00	0.98	1.00	1.00	0.98
128	1.00	1.00	0.98	1.00	1.00	0.98
120	1.00	1.00	0.96	1.00	1.00	0.99
112.9	1.00	1.00	0.98	1.00	1.00	0.98
106.7	1.00	1.00	0.93	1.00	1.00	0.98
101.1	1.00	1.00	0.95	1.00	1.00	0.99
96	1.00	1.00	0.94	1.00	1.00	0.97
91.4	0.99	1.00	0.93	1.00	1.00	0.99
87.3	0.99	1.00	0.90	1.00	1.00	0.98
83.5	0.99	1.00	0.90	1.00	1.00	0.98
80	0.99	1.00	0.92	1.00	1.00	0.97
76.8	0.99	1.00	0.89	1.00	1.00	0.99
73.8	0.98	1.00	0.85	1.00	1.00	0.96
71.1	0.98	1.00	0.86	1.00	1.00	0.96
68.6	0.98	1.00	0.84	1.00	1.00	0.98
66.2	0.98	1.00	0.78	1.00	1.00	0.99
64	0.97	1.00	0.81	1.00	1.00	0.96
61.9	0.97	1.00	0.75	1.00	1.00	0.98
60	0.98	1.00	0.78	1.00	1.00	0.96
58.2	0.97	1.00	0.76	1.00	1.00	0.95
56.5	0.95	1.00	0.72	1.00	1.00	0.97
54.9	0.96	1.00	0.72	0.99	1.00	0.98
53.3	0.93	1.00	0.65	1.00	1.00	0.97
51.9	0.95	1.00	0.68	0.99	1.00	0.96
50.5	0.95	1.00	0.63	0.99	1.00	0.94
49.2	0.94	1.00	0.58	0.99	1.00	0.96
48	0.93	1.00	0.63	0.99	1.00	0.96

Color Key:	Excellent (≥ 0.90)	Good (0.75-0.89)
	Moderate (0.50-0.74)	Poor (< 0.50)

